OMRON

FH-1050 FH-3050 FH-1050-□0 FH-3050- 0

Image Processing System

INSTRUCTION SHEET

Thank you for selecting OMRON product. This sheet primarily describes precautions required in installing and

marily describes precautions required in installing and operating the product.

Before operating the product, read the sheet thoroughly to acquire sufficient knowledge of the product. For your convenience, keep the sheet at your disposal.

THACEABILITY MORPOMIATION.

Representation in EU

Option Europe 8 V.

Option Europe 8 V.

Option Europe 8 V.

Application Sensors Division

The Netherlands.

Sensor Option Sensors Division

Sensor Option Se

N:
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rypuo, 600-6530 JAPAN

following notice applies only to products that carry the CE mark: ice: s is a class A product. In residential areas it may cause radio rference, in which case the user may be required to take ade asures to reduce interference.



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Meanings of Signal Words

Symbols and the meanings for safety precautions described in this manual.

In order for the product to be used safely, the following indications are used in this book to draw your attention to the cautions. The cautions with the indications describe the important contents for safety.



Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage.

⚠ CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

Meanings of Alert Symbols

The following alert symbols are used in this manual. Indicates general prohibitions for which there is



Indicates the possibility of electric shock under specific conditions.



Indicates the possibility of explosion under specific conditions.



indicates the possibility of laser radiation.



Indicates the possibility of injury by high

Alert statements in this Manual

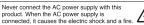
The following alert statements apply to the products in this manual. Each alert statement also appears at the locations needed in this manual to attract your attention.

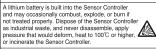
MARNING

This product must be used according to the instruction manual. Failure to observe this may result in impairment of functions and performance of the product.



This product is not designed or rated for ensuring safety of persons. Do not use it for such purposes.





Since camera that can be connected with this product emits a visible light that may have an adverse effect on the eyes, do not stare directly into the light emitted from the LED. If a specular object is used, take care not to allow reflected light enter your eyes.



Do not touch the terminals while the power supply s ON. Doing so may result in electrical shock.

Please take external safety measures so that the system as a whole should be on the safe side even if a failure of a Sensor Controller or an error due to an external factor occurred.An abnormal operation may result in serious accident.



Please take fail-safe measures on your side in preparation for an abnormal signal due to signal conductor disconnection and/or momentary power interruption.An abnormal operation may result in a serious accident.



⚠ CAUTION

Danger of burns. Do not touch the case while the LED is ON or just after power is turned OFF, since it remains extremely hot.



Precautions for Safe Use

- Installation Environment
 Do not use the product in areas where flammable or explosive
- up not use the product in areas where flammable or explosive gases are present.
 Install the product so that air can flow freely through its cooling vents.
 Clean the vent hole and discharge opening to prevent dust or particles from blocking them. Blocked cooling vents or discharge opening of the fan increasing heat inside, causing malfunction of the product.
- Do not install the product close to high-voltage devices and power devices in order to secure the safety of operation and
- maintenance.

 Make sure to tighten all installation screws securely.

●Prover Supply and Wring

• Makes due to up the product with the power supply voltage

• Makes Supply out the product with the power supply voltage

• Lise the specified wire size (AWG10 to 16).

• Keep the prover supply wires as short as possible (Max.2m).

• Use a DC power supply wire supply wires as short as possible (Max.2m).

• Use a DC power supply with safety measures against high-voltage splkes(safety eartie low-voltage circuits or the secondary side).

• Supply (Max.2m) and (Max.2m).

Do the following continemations again before turning on the pow supply.

- Is the voltage and polarily of the power supply correct (24VDC) -- Is not the load of the output signal short-circuited?

- Is the load current of the output signal appropriate?

- Is not the mistake found in wings?

- Is not the mistake found in wings?

- Is the voltage and polarily of the encoder power(ENCO VDD / ENCO GND / ENCS IV DD / ENC1 GND) supply? (GVDC)

GENERAL GRUD FENCH VIDU FENCH GRUD supply 7 (SWDC).

GENERAL GRUD Supply circuit of the FFR Sensor Controller is insulated from the internal circuit.

Be sure to use a base to install the camera connected with the FFR Sensor Controller. Since the exclosure of the camera main body made of metals is short-circuited with the internal circuit, the internal circuit might be short-circuited with FG if no base is used, so that failures or malfunctions may be caused.

Perform Class D-class grounding (with a grounding resistance of Ferton Class Control of the Cont

TOURZ OF IESS).

Keep the ground line as short as possible by setting the grounding noint as close as possible.

point as close as possible.

Ground the FH Sensor Controller independently. If sharing the ground line with other devices or connecting it with a building beam, the Sensor Controller might be adversely effected.

Check wiring again before turning on the FH Sensor Controller.

Other

er only the camera and cables designed specifically for the duct. Use of other products may result in malfunction or damage

The state of the products may resum a management of the product of

cable with power supplied may result in damage of the camera or perspheral deviate fleet of repeatedly, use the robulc table type robust metal cable) to prevent damages.

For the cable that seed of repeated was the robust cable type repeated to the robust metal cable) to prevent damages.

Do not apply orison stress to the cable. It may damage the cable. Secure the minimum bending radius of the cable. Otherwise the cable may be damaged.

Do not attempt to dismanifact or modify the product.

Do not attempt to dismanifact or modify the product.

The FH Sensor Controller and camera case are hot while power is supplied or directly after the FH Sensor Controller is turned off. Do not dough the case.

The Sensor Controller and camera case are hot while power is supplied or directly after the FH Sensor Controller is turned off. Do not dough more excessive withcallor or shock on the product. Doing so may result in malfunction or burning.

Since all this unbattery is incorporated, there is a rare case when you are seriously injured due to firing or blowout.

Regulations and Standards
 The FH Sensor Controller is compliant with the standards

below: EC Directive, 2004/108/EC EN (European Norm), EN61326-1 UL standard, UL508

●Regulations of KC marking A 급 기기 (업무용 방송통신기자재) 이 기기는 업무용(A 급) 전자파적합기기로서 판매자 또는 사용자는 이 점을 주의하시기 바라며 가정의의 지역에서 사용하는 것을 목적으로 합니다.

Precautions for Correct Use

- Unstallation and Storage Sites Install and store the product in a location that meets the following conditions:
- conditions:

 Surrounding temperature of 0 to 50°C (-20 to +65°C in storage)

 No rapid changes in temperature (place where dew does not form)

 Relative humidity to between 35 to 65 %

 No presence of corrosive or flammable gases

 Place free of dust, salts and iron particles

 Place tree of dust, salts and iron particles

 Place until officet sunlight

 Place until officet sunlight

 Place where it will not come into contact with water, oils or cheoricals.

- chemicals Drientation of Product

To keep proper ventilation, install the main unit only in the direction below so that the ventilation holes are not blocked.



Do not install in this orientation.



● Ambient Temperature

* To keep proper air flow, keep the top of the FH Sensor Controller Somm or more apart from other devices. Install the FH Sensor Controller with a clearance of 30mm on the right, left side, and 15mm for rear planes.

**Imperiment the state of the state o

- Lo not install the product with a cannet containing night-votage equipment in the product within 200 mm of power cables.

- Component Installation and Handling.
- Touching Signal Lines
- To prevent damage from static electricity, use a wrist strap or another device for preventing electrostatic discharges when touching terminals or signal lines in connectors.
- Handling a USB MemorySD memory card, make sure that data is not being read or withen to the data is not being read or withen to this data is sheing read or without so make sure that it is it steadily before removing the memory.

written, so make sure that it is it steamy become any memory.

For SD memory card, the SD BUSY LED flashes while data is being read or written, so make sure that it is turned OFF before being read or written, so make sure that it is turned OFF before the surface of the surfac

- What it is senieus.

 Mariteriance

 Furn OFF the power and take safely precautions before conducting from the power and take safely precautions before conducting the power time of time of the power time of the p

avoid this problem, clear the receiving buffer of your device at initial operations.

It is also Measures
If you wish to operate a stage and/or a robot using a measurement result from a FH Sensor Controller(e.g., axis movement amount output based on calibration/alignment measurement, always take safety measures so that the measurement result should be checked by the stagerboot it is within the range of movement of the stagerboot before operation. Supplementarily use operations and branches of the FH Sensor Controller to configure a check flow such as "data should not be externally provided if the data is in a range from-XXXXX to XXXXX"based on the stage/robots range of movement.

■Basic Configuration

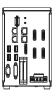
Items indicated with an asterisk are dedicated items, and cannot be substituted.

Sensor controller

The Sensor Controller performs the image processing specified by the user settings and outputs the measurement results.

Camera 2ch type Camera 4ch type Camera 8ch type FH-3050 FH-3050-10 FH-3050-20 FH-1050 FH-1050-10 FH-1050-20







display the condition-setting menus.



LCD monitor

Use the monitor to check images and

FZ-VM (2m, 5m, min. bending radius: 75mm)

Monitor conversion connector FH-VMRGB

* SD memory card HMC-SD291 HMC-SD491

Camera cable FZ-VS (2m, 5m,10m, min. bending radius: 69mm) Bend resistant camera cable FZ-VSB (2m, 5m, 10m min. bending radius: 69mm) Right-angle camera cable FZ-VSL (2m,5m,10m min. bending radius: 69mm) Long-distance camera cable FZ-VS2 (15m min. bending radius: 93mm) Long-distance Right-angle camera cable FZ-VSL2 (15m min. bending radius: 93mm)

Camera

Camera cable

Detects workpieces as images. Standalone camera FZ-SC/FZ-S/ FZ-SC2M/FZ-S2M/ FZ-SCZW/FZ-SZ FZ-SFC/FZ-SF/ FZ-SPC/FZ-SH/ FH-SC/FH-SM/ EH-SC02/EH-SM02/ FH-SC02/FH-SM02/ FH-SC04/FH-SM04/ FZ-SC5M2/FZ-S5M2/ FH-SC12/FH-SM12 Intelligent compact camera FZ-SQ010F/FZ-SQ050F/ FZ-SQ100F/FZ-SQ100N

Peripheral Device

* USB memory FZ-MEM2G FZ-MFM8G

Power Supply

The power supply connected to FH Sensor Controller varies depending on the number of connected cameras and types for various consumption current types. Use is accordingly.

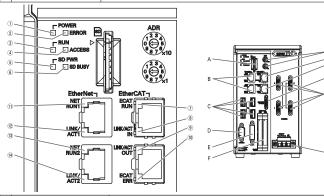
Consumption Carrier types, use a according Recommended Model by OMRON: S8VS series S8VS-09024, S8VS-12024 S8VS-18024, S8VS-24024 S8VS-48024

Input Device

Mouse, keyboard (Commercially available USB devices)

■ Component Names and Functions

	•						
	LED name	Description					
1	POWER LED	Lit while power is ON.					
2	ERROR LED	Lit when an error has occurred.					
3	RUN LED	Lit while the layout turned on output setting is displayed.					
4	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.					
(5)	SD POWER LED	Lit while power is supplied to the SD memory card and the card is usable.					
6	SD BUSY LED	Blinks while the SD memory card is accessed.					
7	EtherCAT RUN LED	Lit while EtherCAT communications are usable.					
8	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.					
9	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.					
10	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.					
(1)	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.					
(12)	EtherNet NET LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.					
13	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.					
14	EtherNet NET LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.					



	Connector name	Description						
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.						
В	EtherNet connector	Connect an EtherNet device.						
		Camera 2ch type Camera 4ch / 8ch type						
		Ethernet port and EtherNet/IP port are sharing use.						
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement. Measurement time might be affected otherwise.						
D	RS-232C connector	Connect an external device such as a PLC.						
Е	DVI-I connector	Connect a monitor.						
F	I/O(Parallel) connector(control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.						
G	EtherCAT address setup volume	Used to set a station address (00 to 99) as an EtherCAT communication device.						
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.						
1	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.						
J	Encoder connector	Connect an encoder.						
K	Camera connector	Camera connector No. is consistent with Camera Image Input No. of Sensor controller software. Check and connect them.						
L	Power supply terminal connector	Connect a DC power supply. Wire the FH Sensor Controller independently on other devices. Wire the ground line. Be sure to ground the FH Sensor Controller alone. Perform wiring using the attached terminal block connector as referring to the description of wiring that connector.						

■Parallel Interface

Common use to all NPN/PNP models. Wire appropriately according to the specification of the external device. Internal Specification (for NPN Connection)

[Input] Applicable signals/ No.14 pin : Connect the COMIN1 te

.14 pin : Connect the COMIN1 terminal when using these signals. 37 to 46 pins : Connect the COMIN2 terminal when using these signals.						
Input voltage	12-24VDC ±10%					
ON current *1	Min. 5mA					
ON voltage *1	Min. 8.8V					
OFF current *2	Max. 0.5mA					
OFF voltage *2	Max. 1.1V					
ON delay	5ms or less					
OFF delay	0.7ms or less					
Internal circuit diagram	COM IN Each irput terminal					

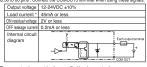
*1 ON current/voltage means the current or voltage value to activate the terminal. The ON voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/ No.15 to 19 pin, No.28 to 32pin : Connect the COMOUT0 terminal when using

these signals.

No.48 to 57 pins: Connect the COMOUT2 terminal when using these signals.

No.58 to 66 pins: Connect the COMOUT3 terminal when using these signals.



* The current value must be the specified load current or lower.
Exceeding the specified current value may cause damage of the output circuit.

●Internal Specification (for PNP Connection)

[Input] Applicable signals/ No.14 pin : Connect the COMIN1 terminal when using these signals. No.37 to 46 pint : Connect the COMIN2 terminal when using these signals

Input voltage	12-24VDC ±10%
ON current *1	Min. 5mA
ON voltage *1	Min. 8.8V
OFF current *2	Max. 0.5mA
OFF voltage *2	Max. 1.1V
ON delay	5ms or less
OFF delay	0.7ms or less
Internal circuit diagram	Each input terminal

[Output] Applicable signals/ No.15 to 19 pin, No.28 to 32 pin : Connect the COMOUT0 terminal

when using these signals.

No.48 to 57 pins: Connect the COMOUT2 terminal when using these signals.

No.58 to 66 pins: Connect the COMOUT3 terminal when using these signals.

Output voltage	12-24VDC ±10%
Load current *	45mA or less
ON residual voltage	2V or less
OFF leakage current	0.2mA or less
Internal circuit diagram	COM CUT

* The current value must be the specified load current or lower.

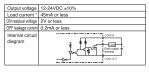
Exceeding the specified current value may cause damage of the output circuit.

[Input] Applicable signals/
No.4 to 6, 9 to 11 pins : Connect the COMIN1 terminal when using these signals.

.7, 8, 12, 13 pins : Connect the COMINO terminal when using these signals.						
Input voltage	12-24VDC ±10%					
ON current *1	Min. 5mA					
ON voltage *1	Min. 8.8V					
OFF current *2	Max. 0.5mA					
OFF voltage *2	Max. 0.8V					
ON delay	0.1ms or less					
OFF delay	0.1ms or less					
Internal circuit diagram	COM N					

*2 OFF current/voltage means the current or voltage value to deactivate the terminal. The OFF voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/ No.20 to 27 pins : Connect the COMOUT1 and COMIN0 terminals when using these signals.



Input voltage	12-24VDC ±10%
ON current *1	Min. 5mA
ON voltage *1	Min. 8.8V
OFF current *2	Max. 0.5mA
OFF voltage *2	Max. 0.8V
ON delay	0.1ms or less
OFF delay	0.1ms or less
Internal circuit diagram	Each Input Neminal

2 OFF current/voltage means the current or voltage value to activate the terminal. The OFF voltage value is the potential difference between COM IN and each input terminal.

[Output] Applicable signals/ No.20 to 27 pins : Connect the COMOUT1 and COMIN0 terminals when using these signals.

Output voltage	12-24VDC ±10%
Load current *	45mA or less
ON residual voltage	2V or less
OFF leakage current	0.2mA or less
Internal circuit diagram	Esch output Interview COM N

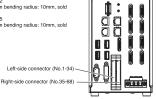
The role of terminals varies depending on the settings of FH Sensor Controller. Check the settings and perform correct wiring.

			Signa	Remarks						
No	1/0	In the 1-line mode	In the 2-line random mode	Tromeina						
1	-		COI							
2	-		COI							
3	- IN	STEPOENCTRIG ZO (*1)	STEPOENCTRIG ZO (*2)	STEPO						
5	IN	Unused (*5)	STEPSENCTRIG ZS (2)							
6	IN	Unused (*5)	Unused (*5)							
7	IN	Unused (*5)	Unused (*5)	STEP2 STEP3	STEP2 STEP3					
8	IN	ENCTRIG_AO (*1)	ENCTRIG A0 (*2)	Unused (*5)	Unused (*5)					
9	IN	Unused (*5)	Unused (*5)	Unused (*5)	STEP4					
10	IN	Unused (*5)	Unused (*5)	Unused (*5)	STEP5					
11	IN	Unused (*5)	ENCTRIG_A1 (*2)	Unused (*5)	STEP6					
12	IN	Unused (*5)	ENCTRIG_B1 (*2)	Unused (*5)	STEP7					
13	IN	ENCTRIG_B0 (*1)	ENCTRIG_B0 (*2)	Unused (*5)	Unused (*5)					
14	IN	Unused (*5)		NE0	I					
15	OUT	RUN0 READY0	RUN0 READY0	RUN0 READY0	READY0 BUSY0	4				
17	OUT	BUSY0	BUSY0	BUSY0	OBO					
18	OUT	OB0	OR0	OR0	READY1					
19	OUT	EBBOB0	ERROR0	ERROR0	BUSY1					
20	OUT	STGOUTO ("3)/SHTOUTO	STGOUTO ("3)/SHTOUTO	STGOUTO ("3)/SHTOUTO	STGOUTO ("3)/SHTOUTO					
21	OUT	STGOUT1 (*3)	STGOUT1 (*3)/SHTOUT1	STGOUT1 (*3)/SHTOUT1	STGOUT1 (*3)/SHTOUT1					
22	OUT	STGOUT2 (*3)	STGOUT2 (*3)	STGOUT2 (*3)/SHTOUT2	STGOUT2 (*3)/SHTOUT2					
23	OUT	STGOUT3 (*3)	STGOUT3 (*3)	STGOUT3 (*3)/SHTOUT3	STGOUT3 (*3)/SHTOUT3	COMINO to 2 : Common 0 to 2 for input signals				
24	OUT	STGOUT4 (*3)	STGOUT4 (*3)	STGOUT4 (*3)	STGOUT4 (*3)/SHTOUT4	COMOUT0 to 3 : Common 0 to 3 for output signals				
25	OUT	STGOUT5 (*3)	STGOUT5 (*3)	STGOUT5 (*3)	STGOUTS (*3)/SHTOUTS					
26	OUT	STGOUT6 (*3)	STGOUT6 (*3)	STGOUT6 (*3)	STGOUT6 (*3)/SHTOUT6	DI0 to 7 : Command inputs				
27	OUT	STGOUT7 (*3)	STGOUT7 (*3)	STGOUT7 (*3)	STGOUT7 (*3)/SHTOUT7	DILINEO to 2 : Command inputs (line specified)				
28 29	OUT	Unused (*5) Unused (*5)	RUN1 READY1	RUN1	OR1 READY2	DSA0 to 1 : Data transmission request				
	OUT		BUSY1	READY1		ENCTRIG_A0 to 1 : Encoder trigger input (phase A)				
30	OUT	Unused (*5) Unused (*5)	OR1	BUSY1 OR1	BUSY2 OR2	ENCTRIG_80 to 1 : Encoder trigger input (phase8) ENCTRIG_20 to 1 : Encoder trigger input (phase Z)				
32	OUT	Unused (*5)	ERROR1	ERROR1	READY3	STEP0 to 7: Measurement trigger input				
33	-	Oliuseu (3)		OUTO	INCADIO	31EFOLD 7 - Illeasurenient tigger tiput				
34	-			OUT1		ACK : Instruction execution completion flag				
						BUSY0 to 7 : ON during processing				
35	-		COI	MIN2		DO0 to 15 : Data output				
36	-		Va	icant		ERROR: ON when an error occurs (*4)				
37	IN	DSA0	DSA0			ERROR0 to 3 : ON when an error occurs				
38	IN	Unused (*5)	DSA1	Unused (*5)	DILINE2	GATE0 to 1 : ON during configured output time				
39	IN		D			OR0 to 7 : Overall judgement result				
40	IN		D			READY0 to 7: ON when image input is allowed				
41	IN IN		D D			RUN0 to 3 : ON while the layout turned on output setting is displayed				
43	IN		D			SHTOUT0 to 7 : Shutter output				
44	IN		D			STGOUT0 to 7 : Strobe trigger output(*3)				
45	IN		D							
46	IN		D							
47	-			cant						
48	OUT		AC							
49	OUT	GATE0	GATE0	RUN2	BUSY3					
50	OUT	Unused (*5)	GATE1	READY2	OR3					
51	OUT	DO0	DO0	BUSY2	READY4					
52	OUT	DO1	DO1	OR2	BUSY4					
53	OUT	DO2	DO2	ERROR2	OR4					
54	OUT	DO3 DO4	DO3	RUN3 READY3	READY5 BUSY5					
56	OUT	DO5	D05	BUSY3	OR5					
57	OUT	D06	D06	OR3	READY6					
58	OUT	D07	D07	ERROR3	BUSY6					
59	OUT	DO8	DO8	Unused (*5)	OR6					
60	OUT	DO9	DO9	Unused (*5)	READY7					
61	OUT	DO10	DO10	Unused (*5)	BUSY7					
62	OUT	D011	DO11	Unused (*5)	OR7					
63	OUT	DO12	DO12	Unused (*5)	Unused (*5)					
64	OUT	DO13	DO13	Unused (*5) Unused (*5)	Unused (*5)					
65	OUT	DO14	DO14	Unused (*5)						
66	OUT	DO15	DO15 COM	ERROR (*4)						
68	-			OUT2 OUT3						
00	_	l	COM							

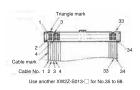
1 To use a measurement trigger input, use the STEP signal. To use an encoder input, use ENCTRIG_A0/B0/20.
2 In the 2-line random mode, to use a measurement trigger input and a line of encoder input, use ENCTRIG_A0/B0/20 and STEP1.
3 This is the signal used when using a strobe signal for the FH Sensor Controller.
4 This is the ERROR signal commonly used in 1 to 8-line modes.
5 Do not connect anything for Unused.

Connection

Connect the parallel I/O cable with more than the minimum bending radius. XW2Z-S013-2 (2m, minimum bending radius: 10mm, sold separately) XW2Z-S013-5 (5m, minimum bending radius: 10mm, sold separately)



Pin Assignment



■Encoder Interface (Line Driver Type)

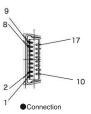
● Specification of Encoder Interface (Line Driver Output Type)

Item	Specifications
Input voltage	Input voltage: 5VDC±5% Signal level: EIA Standard, RS-422-A line driver level
Input impedance *1	120Ω±5%
Differential input voltage	High-level input voltage I 0.1V, Low-level input voltage I -0.1V
Hysteresis voltage	60mV
Maximum response frequency *2	Phase A/B: single-phase 4MHz (multiplying phase difference of 1MHz by 4 times), Phase Z: 1MHz (When using an I/O cable, model FH-VR 1.5M)

*1 Value when the terminal resistance function is used.
*2 Use this interface as paying attention to the cable length and response frequency of the encoder used.

■I/O Connector

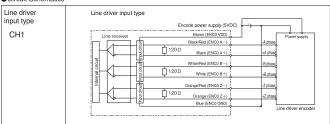
TI/O Confrector							
No	Signal name	Color	Remarks				
-1	ENC0 A+	Black	Signal : Ch1 A-Phase(+)				
2	ENC0 A-	Black /Red	Signal : Ch1 A-Phase(-)				
3	ENC0 VDD	Brown	Power : Power supply for Ch1 (5VDC)				
4	ENC0 B+	White	Signal : Ch1 B-Phase(+)				
5	ENC0 B-	White/Red	Signal : Ch1 B-Phase(-)				
6	ENC0 GND	Blue	Power : Signal ground for Ch1 (0V)				
7	ENC0 Z+	Orange	Signal : Ch1 Z-Phase(+)				
8 ENC0 Z-		Orange/Red	Signal : Ch1 Z-Phase(-)				
9	NC	-	Not connected				
10	ENC1 A+	Purple	Signal : Ch2 A-Phase(+)				
11	ENC1 A-	Purple/Red	Signal : Ch2 A-Phase(-)				
12	ENC1 VDD	Brown/Red	Power : Power supply for Ch2 (5VDC)				
13	ENC1 B+	Pink	Signal : Ch2 B-Phase(+)				
14	ENC1 B-	Pink/Red	Signal : Ch2 B-Phase(-)				
15	ENC1 GND	Blue/Red	Power: Signal ground for Ch2 (0V)				
16	ENC1 Z+	Yellow	Signal : Ch2 Z-Phase(+)				
17	ENC1 Z-	Yellow/Red	Signal : Ch2 Z-Phase(-)				

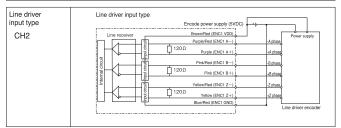


Connect the encoder cable with more than the minimum bending radius FH-VR 1.5M (1.5m, minimum bending radius: 65mm, sold separately)



●Circuit Schematics





■ Camera cable

The maximum cable length depends on the Camera being connected,and the model and length of the Cable being used. For further information, please refer to the "Camera/Cables Connection Table". Be sure to secure at least the minimum bending radius of the cable.

● Cameras/Cables Connection Table(Connecting to FH-S Series Camera)

				High-speed CMOS cameras *						
	Model	Cable length	300,000-pixel 2 million-pixel		4 million-pixel		12 million-pixel			
Type of			FH-SM/SC	FH-SM02/SC02		FH-SM04/SC04		FH-SM12/SC12		
camera			-	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	
Camera Cable	FZ-VS	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle	FZ-VSL	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cable		10 m	Yes	No	Yes	No	Yes	No	Yes	
Bend resistant	FZ-VSB	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cable		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Garriora Gabio		10 m	Yes	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZ-VSL2	15 m	Yes	No	Yes	No	Yes	No	Yes	

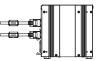
* High-speed CMOS camera is only for the FH series.

tion Table(Connecting to FZ-S Series Camera)

		Cable length		igital CCD camer	as	Small digital	High-speed	Intelligent	
Type of	Model		300,000-pixel 2 million-pixel 5 million-pixel		CCD cameras Pen type/flat type	CCD camera	compact CMOS cameras		
camera		longin	FZ-S/SC	FZ-S2M/SC2M	FZ-S5M2/ SC5M2	FZ-SF/SFC FZ-SP/SPC	FZ-SH/SHC	FZ-SQ□	
Camera Cable Right-angle camera cable	FZ-VS	2 m	Yes	Yes	Yes	Yes	Yes	Yes	
	FZ-VSL	5 m	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	Yes	Yes	No	Yes	Yes	Yes	
Bend resistant	FZ-VSB	2 m	Yes	Yes	Yes	Yes	Yes	Yes	
camera cable		5 m	Yes	Yes	Yes	Yes	Yes	Yes	
Carriera Cabio		10 m	Yes	Yes	No	Yes	Yes	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZ-VSL2	15 m	Yes	Yes	No	Yes	Yes	Yes	

■Mounting of Ferrite core

Mount the ferrite core attached to the camera cable to near the Sensor Controller.



■EtherCAT Interface

● Cable Connect a straight LAN cable.
Use an STP cable of category 5e or higher, which is shielded double with an aluminum tape and a braided cord.

● I/O Connector Use an 8-pin shielded RJ45 modular connecter of category 5e or higher.



Wiring

The cable is maximum 100m long.

However, some cables do not guarantee 100m. If conductor is a twisted cable, transmission performance generally becomes worse than that of straight cables, so that 100m cannot be guaranteed. For details, contact the cable manufacturer.

Pin No.	Wire color		Wire color	Pin No.
1	White · Green	$\vdash \land \vdash$	White · Green	1
2	Green	$\vdash \vdash \vdash$	Green	2
3	White · Orange	\vdash	White · Orange	3
4	Blue	\vdash	Blue	4
5	White · Blue	\vdash	White · Blue	5
6	Orange	\vdash	Orange	6
7	White · Brown	\vdash	White · Brown	7
8	Brown	$\vdash \vdash \vdash \vdash$	Brown	8
Connector hood	Shielded cable		Shielded cable	Connector hood

* Connect both ends of the cable shield with the connector hood.
* Use the T568A wiring method as mentioned above.

■RS-232C(Serial) Interface

●I/O Connector



Wiring

The maximum cable length is 15m.

FH Sensor	r Controller		External device	to be connected
Signal name	Pin No.		Pin No.	Signal name
RD	2	HH	*	RD
SD	3		*	SD
GND	5	-	*	GND
		RS/CS control	cannot be used	
	Use a	shielded cable.		

Pin No.	Signal name	Function		
1	NC	Not connected		
2	RD	Data reception		
3	SD	Data transmission		
4	NC	Not connected		
5	GND	Signal ground		
6	NC	Not connected		
7	NC	Not connected		
8	NC	Not connected		
9	NC	Not connected		



ł		Manufacturer	Model				
l	Sockets	OMRON Corporation	XM3D-0921				
1	Hood	OMRON Corporation	XM2S-0913				
	Hood	OMRON Corporation	XM2S-0913				

Pin numbers will depend on the external device being connected Refer to the manual for the personal computer or PLC being connected.

B

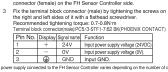
Connection Method
 Align the connector with the socket and press it straight into place, then fix it with the screws on both sides of the connector.

Turn OFF the power supply before connecting or disconnecting a Parallel I/O Cable Peripheral devices may be damaged if the cable is connected or disconnected with

Wiring

[Important] - Wiring cables incorrectly might cause failures. Connection of Terminal Block

- Onnection of lerminal Block Insert the end of the signal line (electric wire) into the terminal block connector (male), and tighten the three screws on the connector top to fix the wire. Recommended tightening torque: 0.7-0.8Nm Insert the terminal block connector (male) into the terminal block connector (female) on the FH Sensor Controller side.



Recommended power supply

Item	Comercian	No. of cameras	High-speed controller			Standard controller		
Item	Camera type	connected	FH-3050	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10	FH-1050-20
Recommended power supply: S8VS	Intelligent compact camera	2	S8VS-12024	S8VS-18024	S8VS-18024	S8VS-12024	S8VS-12024	S8VS-18024
		4	-	S8VS-18024	S8VS-24024		S8VS-18024	S8VS-24024
		8		-	S8VS-48024	-		S8VS-48024
	Camera of 0.3/2/4/5/12 million	2	S8VS-12024	S8VS-18024	S8VS-18024	S8VS-09024	SBVS-09024	S8VS-12024
		4		S8VS-18024	S8VS-18024		SBVS-12024	S8VS-12024
	pixels	8	-	-	S8VS-18024	-		S8VS-18024

■Ratings/Characteristics

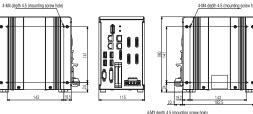
Major	Controller type High-grade (HG) pr	PNP		FH-3050	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10		
Major					FH-3030-10	FH-3050-20	FH-1030	FH-1050-10	FH-1050-20	
Major	High-grade (HG) pr		•	BOX type		•			•	
iviajoi F		High-grade (HG) processing item								
	Number of cameras			2	4	8	2	4	8	
functions	Type of connected camera				be connected (I	FZ-S/FH-S series	}			
	Number of scenes			128						
	Operation			Mouse or simila						
	Settings			Create processi	ng flows by editin	g them (with a gui	dance).			
ŀ	Serial communications			RS-232C 1 CH						
	Ethernet communications			Non-procedural (TCP/UDP) 1000BASE-T						
L	EtherNet/IP communications			1port	2port	2port	1port	2port	2port	
L							use.) Transmissi	on speed: 100Mbp	s (100BASE-TX)	
L	EtherCAT com	munications		EtherCAT dedic	ated protocol (10	0BASE-TX)				
External interface	Parallel I/O			In the 2-line ran In the 3 to 4-line	random trigger r	puts. e: 17 inputs, 37 o node: 14 inputs, 3 node: 19 inputs, 3	29 outputs.			
	Encoder I/F			RS422-A line driver	level. Phase A/B: sin	ngle-phase 4MHz (m.	hiplying phase differ	ence of 1MHz by 4 tir	nes), Phase Z: 1MHz	
	Monitor I/F			DVI-I output 1ch						
Г	USBI/F			4 ch(supports USB1.1 and 2.0)						
- 1	SD memory o	ard I/F		SDHC standard, Class 4 or higher recommended						
	Power supply	voltage		20.4 to 26.4VDC						
H	· cital cappy	When an intelligent compact camera is connected? When a Camera of 0.3/2/4/5/12 million pixels is connected	2 connected	5.0A or less	5.4A or less	6.4A or less	4.7A or less	5.0A or less	5.9A or less	
			4 connected	-	7.0A or less	8.1 A or less	-	6.5A or less	7.5A or less	
	Current consumption *		8 connected	-	-	11.5A or less	_	-	10.9A or less	
Ratings			2 connected	4.1A or less	4.2A or less	5.2A or less	3.6A or less	3.7A or less	4.5A or less	
			4 connected	-	4.8A or less	5.6A or less	-	4.3A or less	5.0A or less	
			8 connected	-	-	6.8A or less	-	-	6.2A or less	
	Insulation resistance			Between DC power supply and FH Sensor Controller FG: 20MΩ or higher (rated voltage					ge 250V)	
	Noise	Fast transient burst	DC power	Direct infusion: 2KV Pulse rising: 5ms Pulse width: 50ns Burst continuation time: 15ms/0.75ms Period: 300ms Application time: 1 min						
	resistance		I/O line	Cramp : 1KV Pulse rising: Sns Pulse width: S0ns Burst continuation time: 15ms/0,75ms Period: 300ms Application time: 1 min						
İ	Ambienttemper	ature range		Operating:0 to 50 °C Storage:-20 to +65 °C (with no icing nor no condensation)						
Operating	Ambienthumidit	y range		Operating and storage:35 % to 85 % (no condensation)						
environment	Ambientenviror	ment		No corrosive gases						
environment -	Grounding			Type D grounding (100Ω or less grounding resistance) *Conventional type 3 grounding						
h	Degree of protes	rtion		IEC60529 IP20						
	Environmental conditions			Indoor use Maximum altitude of 2,000m Supply voltage fluctuations of +10%, -15% of the rated voltage Installation category I Pollution dozene 2						
	Dimensions			190mm(H)×115mm(W)×182.5mm(D)						
Dimensions	Weight Versions			Approx.3.2kg Approx.3.4kg Approx.3.4kg Approx.3.2kg Approx.3.4kg Approx.3.4kg						
	Case materials			Approx.3.2kg Approx.3.4kg Approx.3.2kg Approx.3.4kg Approx						
Content				Cover: zmi-cytaied siere plate; Sale plate: admirrium (Pedos) FH Sensor Controller (1) / Instruction Sheet (one Japanese and one English version) // Instruction Installation Manual (1) / Terminal block connector (1) / Ferrite core 2(FH3050 and FH-1050), 4 (FH-3050-10 and FH-1050-10), and 8 (FH-3050-20 and FH-1050-20)						

The value of power consumption applies when the maximum number of cameras of each FH Sensor Controller is connected with 24VDC. When connecting the lighting with lighting controller, the consumption current is the same as when the intelligent compact camera is connected.

■Dimensions

(Unit: mm)







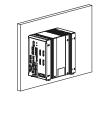
BETABLETONNOMBUR

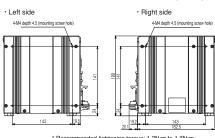
· Camara cable mounting

■Mounting

Tighten the screws securely when installing the product.

Side Mounting

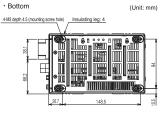




* Recommended tightening torque: 1.2N·m to 1.3N·m *The tolerance is ± 0.2mm.

Bottom Mounting





- * Do not remove the Insulating leg. Fix the Insulating leg to
- secure the ventilation path.

 * Recommended tightening torque: 0.54N·m to 0.6N·m

 *The tolerance is ± 0.2mm.

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See www.dtsc.ca.gov/hazardouswaste/perchlorate