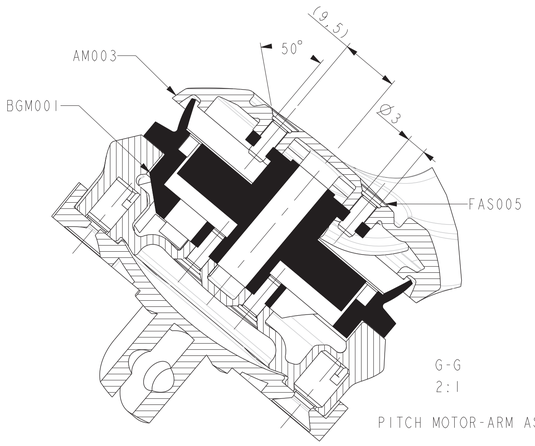
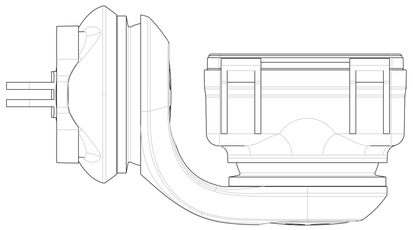
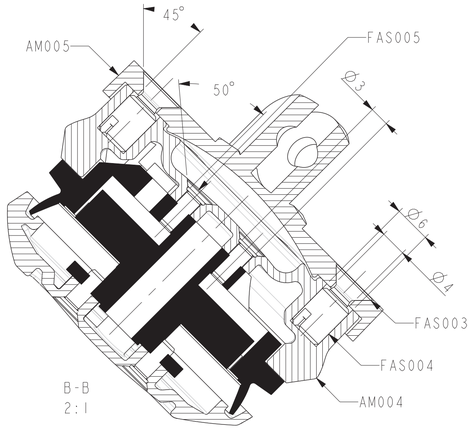


G-G
2:1

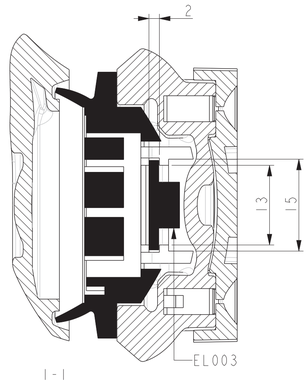
PITCH MOTOR-ARM ASSEMBLY





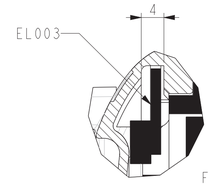
B-B
2:1

COVER PIECE AND HOOK ASSEMBLY



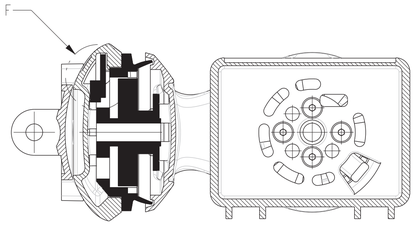
I-I
2:1

IMU BOARD PLACEMENT
BOTTOM VIEW

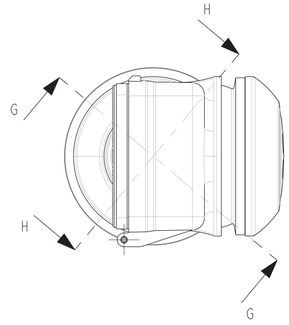


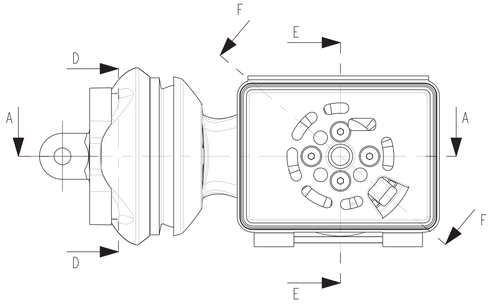
F
2:1

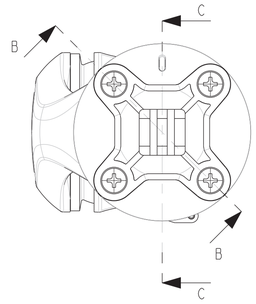
IMU BOARD PLACEMENT
SIDE VIEW

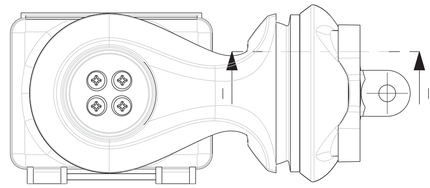


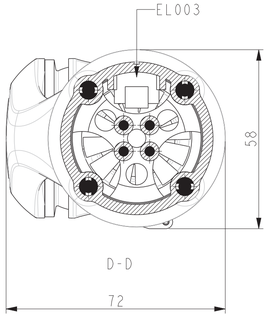
C-C



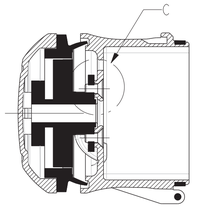




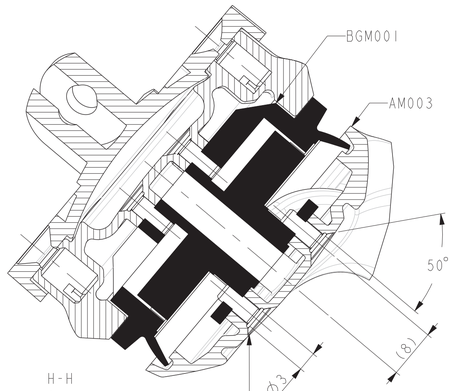




D-D

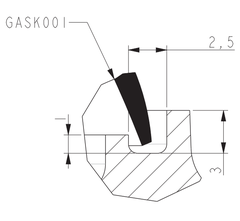


E-E

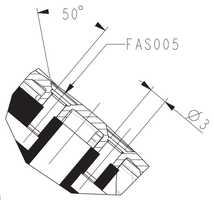


H-H
2:1

PITCH MOTOR-ARM ASSEMBLY

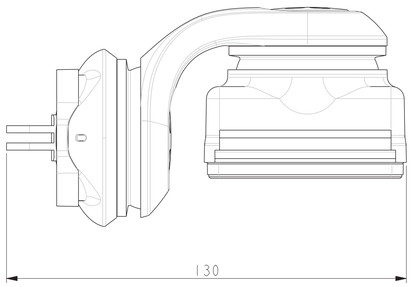


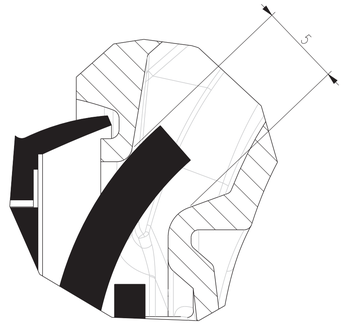
F
2:1



E
2:1

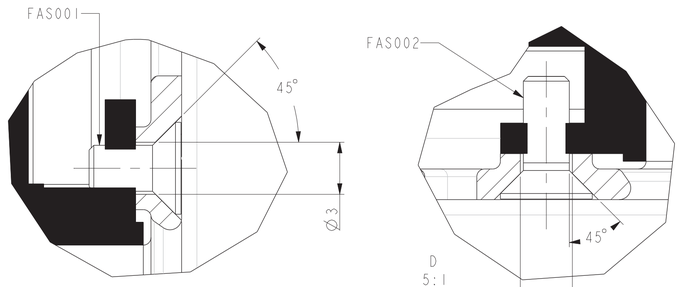
ROLL MOTOR-ARM ASSEMBLY





B
5:1

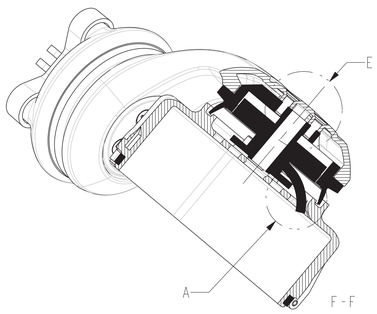
PITCH MOTOR WIRES
ACCESS TO THE ARM

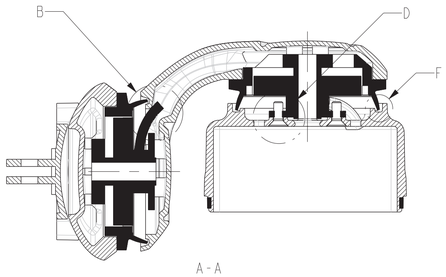


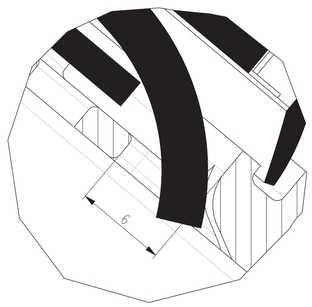
C
5:1

D
5:1

ROLL MOTOR-MAIN CASE ASSEMBLY



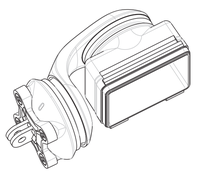


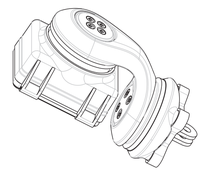


A
5:1

ROLL MOTOR WIRES
ACCESS TO THE MAIN CASE

THE UNSIGNED PARTS REFER TO THE 3D MODEL





Politecnico di Milano

Scuola del Design
CdLM in Design & Engineering
A.A. 2014/2015

Elaborato di Laurea Magistrale

Studente
Davide Caprioli (797030)

Docente relatore
Riccardo Gatti

18/12/2015

POLITECNICO
MILANO 1863

TITLE: Mechanical Hardware assembly details

SHEET 3.2

PROJECT: 2-Axis GoPro Camera Stabilizer

SCALE 1:1